

INSTRUCTION MANUAL

CONTROLS

OUPUT LED

The yellow LED ON indicates the OR function of the three OUT1, OUT2 and OUT3 outputs.

DISPLAY (green 4-digit display)

The display indicates the "run" or "rund" (run with delay) operating mode. Please refer to the "SETTING" paragraph for the correct setup procedure indications.

OUT1, OUT2, OUT 3 LEDs

The green LED ON indicates that the corresponding output is active.

SET PUSHBUTTON

The pressure on the pushbutton activates the self-setting procedure. A long pressure on the pushbutton allows the access to the delay setting menu.

SEL PUSHBUTTON

The pressure allows to scroll through the sensor setting parameter menu. Please refer to the "SETTING" paragraph for the correct setup procedure indications.

INSTALLATION

The sensor can be mounted by means of the three housing's holes using two screws (M4x25 or longer, 1 Nm maximum tightening torque) with washers. The use of fixing brackets is recommended if the supporting surface doesn't have a good planarity. Various orientable fixing brackets to ease the sensor positioning are available (please refer to the accessories listed in the catalogue).

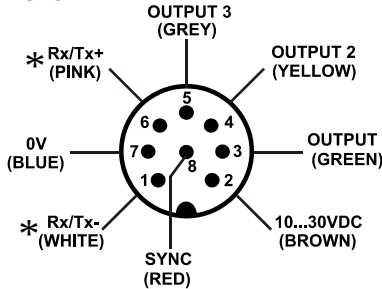
The operating distance is measured from the front surface of the sensor optics.

The M12 connector can be oriented at two different positions using the specific fastening spring and rotating the block of 180°.



CONNECTIONS

M12 CONNECTOR

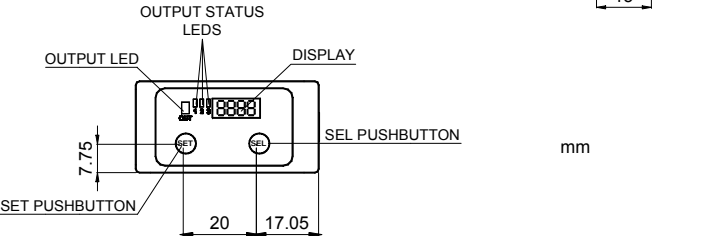
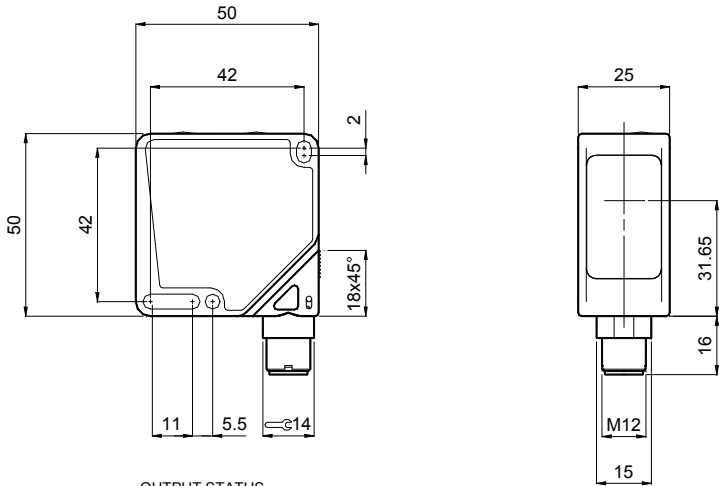


* Available only for version with RS485 serial connection (S65-PA-5-V09-xxxZ).

TECHNICAL DATA

Power supply:	10 ... 30 Vdc limit values Class 2 (UL508)
Ripple:	2 Vpp max.
Consumption (output current excluded):	60 mA max. @ 24Vdc
Outputs:	3 PNP or NPN outputs 30 Vdc max. (short-circuit protection)
Tolerance level:	10 (toL0 - toL9) independent per each channel
Operating mode:	C, C+I independent per each channel
Output current:	100 mA max.
Output saturation voltage:	≤ 2 V
Response time:	335us
Switching frequency:	1.5 KHz
Indicators:	4-digit display (GREEN), OUTPUT LED (YELLOW) 3 OUTPUT STATUS LEDs (GREEN)
Setting:	SET pushbutton, SEL pushbutton
Data retention:	EEPROM non volatile memory
Operating temperature:	-10 ... 55 °C
Storage temperature:	-20 ... 70 °C
Electrical protection:	Class 2
Operating distance (typical values):	20 mm
Minimum spot dimension:	Ø 4 mm
Emission type:	white light LED (400-700nm)
Ambient light rejection:	according to EN 60947-5-2
Vibrations:	0.5 mm amplitude, 10 ... 55 Hz frequency, for every axis (EN60068-2-6)
Shock resistance:	11 ms (30 G) 6 shock for every axis (EN60068-2-27)
Housing material:	ABS
Lens material:	window and lenses in glass
Mechanical protection:	IP67
Connections:	M12 8-pole connector
Weight:	100 g. max.

DIMENSIONS



SETTING

The three-phase sensor setting allows the adjustment of the channel, operating mode and tolerance values.

- pushbutton pressed
- pushbutton not pressed

- Detection

Place object to detect inside the operating distance, in front of the sensor.

OR	1	2	3	Dig1	Dig2	Dig3	Dig4	SET	SEL
■	□	■	□	r	u	n	d	●	○

- Press the SET pushbutton for at least 2s.

- The "Set1" message is visualised.

- Channel setting

OR	1	2	3	Dig1	Dig2	Dig3	Dig4	SET	SEL
□	□	□	□	S	E	t	1	○	●

- Use the SEL pushbutton to select the channel to detection.

OR	1	2	3	Dig1	Dig2	Dig3	Dig4	SET	SEL
□	□	□	□	S	E	t	1	○	●

S	E	t	2	○	●
S	E	t	3	○	●

- Operating mode

- Press the SET pushbutton again to configure the operating mode.

- Select C (colour) or C+I (colour + intensity) using the SEL pushbutton *.

OR	1	2	3	Dig1	Dig2	Dig3	Dig4	SET	SEL
□	□	□	□	C				●	○

C			I	○	●
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- TEACH and tolerance setting

- Press the SET pushbutton again, the "upd1" text blinks for 2s.

The sensor then automatically passes into the tolerance selection.

Use the SEL pushbutton to select the required value.

OR	1	2	3	Dig1	Dig2	Dig3	Dig4	SET	SEL
□	□	□	□	u	p	d	t	●	○

OR	1	2	3	Dig1	Dig2	Dig3	Dig4	SET	SEL
□	□	□	□	t	o	L	0	○	●

t	o	L	1	○	●
t	o	L	2	○	●

t	o	L	...	○	●
t	o	L	9	○	●

- The "FAIL" text alternated with "Hi" or "Lo" is visualised if the detection is not correct.

- Repeat the procedure starting from the operating mode.

NOTE: The 0, 1, 2 tolerance values are particularly suitable for critical applications.

PARAMETER SETTING

Delay value visualisation and setting

OR	1	2	3	Dig1	Dig2	Dig3	Dig4	SET	SEL
■	□	□	■	r	u	n	d	●	○

Press the SET pushbutton for at least 6s to access to the delay setting mode.

OR	1	2	3	Dig1	Dig2	Dig3	Dig4	SET	SEL
□	□	□	□	d	-	0	0	○	●

d	-	0	5	○	●
d	-	1	0	○	●

d	-	2	0	○	●
d	-	3	0	○	●

d	-	4	0	○	●
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At each pressure of the SEL pushbutton, the different delay levels in ms are visualised in a cyclical manner at the output deactivation and moreover, the relative delay value will be stored. When the "d-00" message is visualised the operating mode will be "run", and "rund" in all other cases.

The delay value setting is in common for all three outputs.

When a delay value, different from zero, is set the outputs will be maintained active for a minimum time, which is equal to the number of milliseconds visualised on the display.

d-00 = 0 ms
d-05 = 5 ms
d-10 = 10 ms
d-20 = 20 ms
d-30 = 30 ms
d-40 = 40 ms

Channel status visualisation

This function allows a rapid control of the three sensor channel adjustment.

Pressing the SEL pushbutton for at least 2 s the channel, operating mode and tolerance are visualised in a sequential manner.

OR	1	2	3	Dig1	Dig2	Dig3	Dig4	SET	SEL
■	□	□	■	r	u	n	d	●	○

OR	1	2	3	Dig1	Dig2	Dig3	Dig4	SET	SEL
■	□	□	□	C	h	-	1	○	●

C			I	↓
---	--	--	---	---

t	o	L	2	↓
---	---	---	---	---

C	h		2	↓
---	---	--	---	---

C				↓
---	--	--	--	---

t	o	L	1	↓
---	---	---	---	---

C	h		3	↓
---	---	--	---	---

C				↓
---	--	--	--	---

t	o	L	8	↓
---	---	---	---	---

d	-	0	5	↓
---	---	---	---	---

OR	1	2	3	Dig1	Dig2	Dig3	Dig4	SET	SEL
■	□	□	■	r	u	n	d	●	○

At the end of the sequence the display will indicate the "run" or "rund" operating mode again.

Non-initialised E2PROM

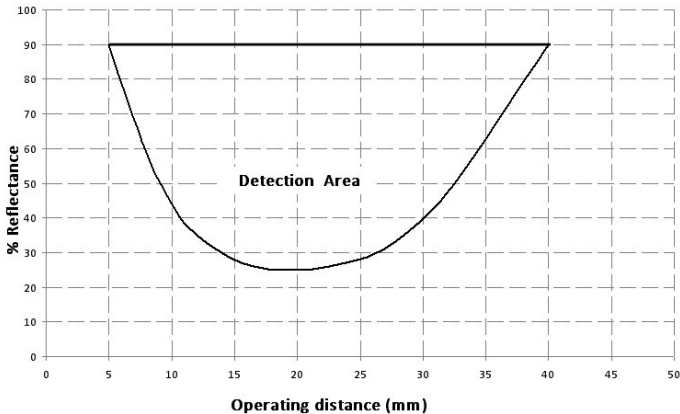
If the display indicates "E2Pr" the sensor does not have any of the three channels initialised.

OR	1	2	3	Dig1	Dig2	Dig3	Dig4	SET	SEL
□	□	□	□	E	2	P	r	○	○

In this case it is sufficient to program one single channel to obtain the "run" or "rund" visualisation on the display.

* The 'C' type algorithm is used to obtain a larger depth of field, or to detect colours on different opaque, shiny or reflecting surfaces. Whereas the 'C+I' type algorithm offers a higher sensitivity towards tone variations and is recommended for the detection of different colours on the same type of material, with the possibility of distinguishing also the grey tones.

DETECTION DIAGRAM



REMOTE FUNCTIONS

KEYLOCK function (SET pushbutton block)

If at sensor powering the SYNC wire is connected to +Vdc for at least 1s, the keylock function is activated and the pushbuttons are no longer active.

After the first second, the SYNC input is available for the normal operating modes; if SYNC is high the outputs are deactivated.

To deactivate the keylock, the sensor has to be turned off and re-powered with the SYNC wire not connected or ground connected (GND).

SYNC input

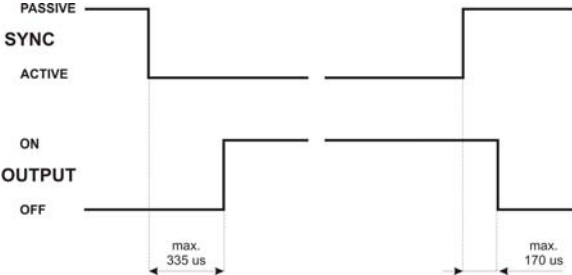
The SYNC signal can exactly determine the beginning and end of the colour identification.

The identification cycle begins after the SYNC signal changes from passive to active and the sensor outputs have to updated after max. 335µs.

All the outputs are deactivated after max. 170µs from an active passage to a passive one.

The connection of the SYNC wire to Vdc corresponds to the passive logic status while SYNC not connected or connected to 0V corresponds to the active logic status.

(SYNC passive = Vdc ; SYNC active = 0V)



A typical application is a multicoloured target where the colour to detect is in a determinate position, while the other zones have to be faded out. Moreover, incorrect detections can be avoided during transition from the target to the background.

RS485 serial connection only for version S65-PA-5-V09-xxxZ

The complete sensor remote control is possible using the RS485 line.

All the functions such as the channel selection, the tolerance selection and the operating mode can be accessed by means of this serial line.

The serial communication parameters are: 9600 baud, no equity, 8 data bits, 1 stop bit.

All the commands have to be sent via terminal in an ASCII format as follows:

- Receiving of the channel status:

At any moment, the receipt of the 'r <CR> <LF>' command indicates the sensor configuration.

- Remote setting mode:

To access to the remote setting mode, the SYNC input has be remain passive for at least 300ms.

The commands available are given below:

@ <CR> <LF> beginning of the remote setting (together with passive SYNC)

cx <CR> <LF> channel selection, with x ∈ {1,2,3}

tx <CR> <LF> tolerance selection, with x ∈ {0,1,2,3,4,5,6,7,8,9}

mx <CR> <LF> operating mode selection, with x ∈ {1,2}

m1 = C

m2 = C+I

e <CR> <LF> configuration sequence activation.

q <CR> <LF> exit from the remote setting mode without saving configuration.

If the SYNC input is activated before the 'e' (execute) command is given, the sensor exits the remote setting mode without saving the configuration, similarly to the receipt of the 'q' (quit) command.

If the SYNC input is active, at the receipt of the @ <CR> <LF> command, the sensor responds with: ?? <CR> <LF>. At the receipt of the q <CR> <LF> or e <CR> <LF> commands, the sensor transmits ok <CR> <LF>.

The lo <CR> <LF> message is transmitted if the signal is too low and hi <CR> <LF> if the signal is too high.

- Delay configuration:

To access to the delay configuration, the SYNC input has be remain passive for at least 300 ms The commands available are given below:

@ <CR> <LF> beginning of the delay configuration (together with passive SYNC)

dx <CR> <LF> delay selection, with x ∈ {0,1,2,3,4,5}

d0 = 0 ms d3 = 20 ms

d1 = 5 ms d4 = 30 ms

d2 = 10 ms d5 = 40 ms

e <CR> <LF> memorisation of the new delay value

q <CR> <LF> exit from the delay configuration without saving the configuration.

If the SYNC input is activated before the 'e' (execute) command is given, the sensor exits the remote setting mode without saving the configuration, similarly to the receipt of the 'q' (quit) command.

If the SYNC input is active, at the receipt of the @ <CR> <LF> command, the sensor responds with: ?? <CR> <LF>. At the receipt of the q <CR> <LF> or e <CR> <LF> commands, the sensor transmits ok <CR> <LF>.

NOTE: during the command transmission, the single strings have to follow each other with a delay of at least 1ms.

The sensors are NOT safety devices, and so MUST NOT be used in the safety control of the machines where installed.

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